Industrial Automation
(Automação de Processos Industriais)

PLCs Programming Languages
Instruction List

http://users.isr.ist.utl.pt/~jag/courses/api1112/api1112.html

Slides 2010/2011 Prof. Paulo Jorge Oliveira
Rev. 2011/2012 Prof. José Gaspar

Syllabus:

Chap. 2 – Introduction to PLCs [2 weeks]

...

Chap. 3 – PLCs Programming Languages [2 weeks]

Standard languages (IEC-1131-3):

Ladder Diagram; Instruction List, and *Structured Text.*

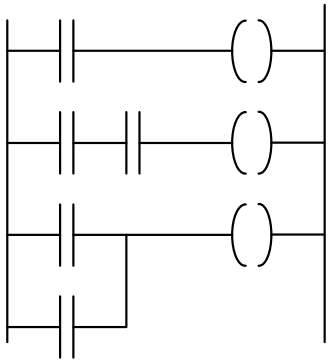
Software development resources.

...

Chap. 4 - GRAFCET *(Sequential Function Chart)* [1 week]

PLCs Programming Languages (IEC 1131-3)

Ladder Diagram



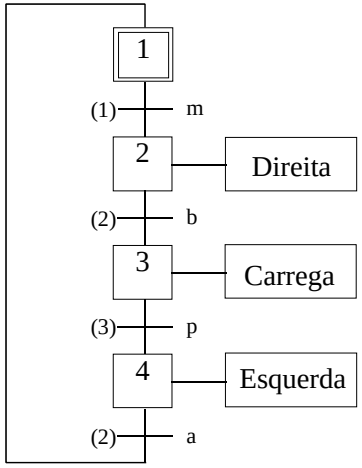
Structured Text

```
If  %I1.0  THEN
  %Q2.1 := TRUE
ELSE
  %Q2.2 := FALSE
END_IF
```

Instruction List

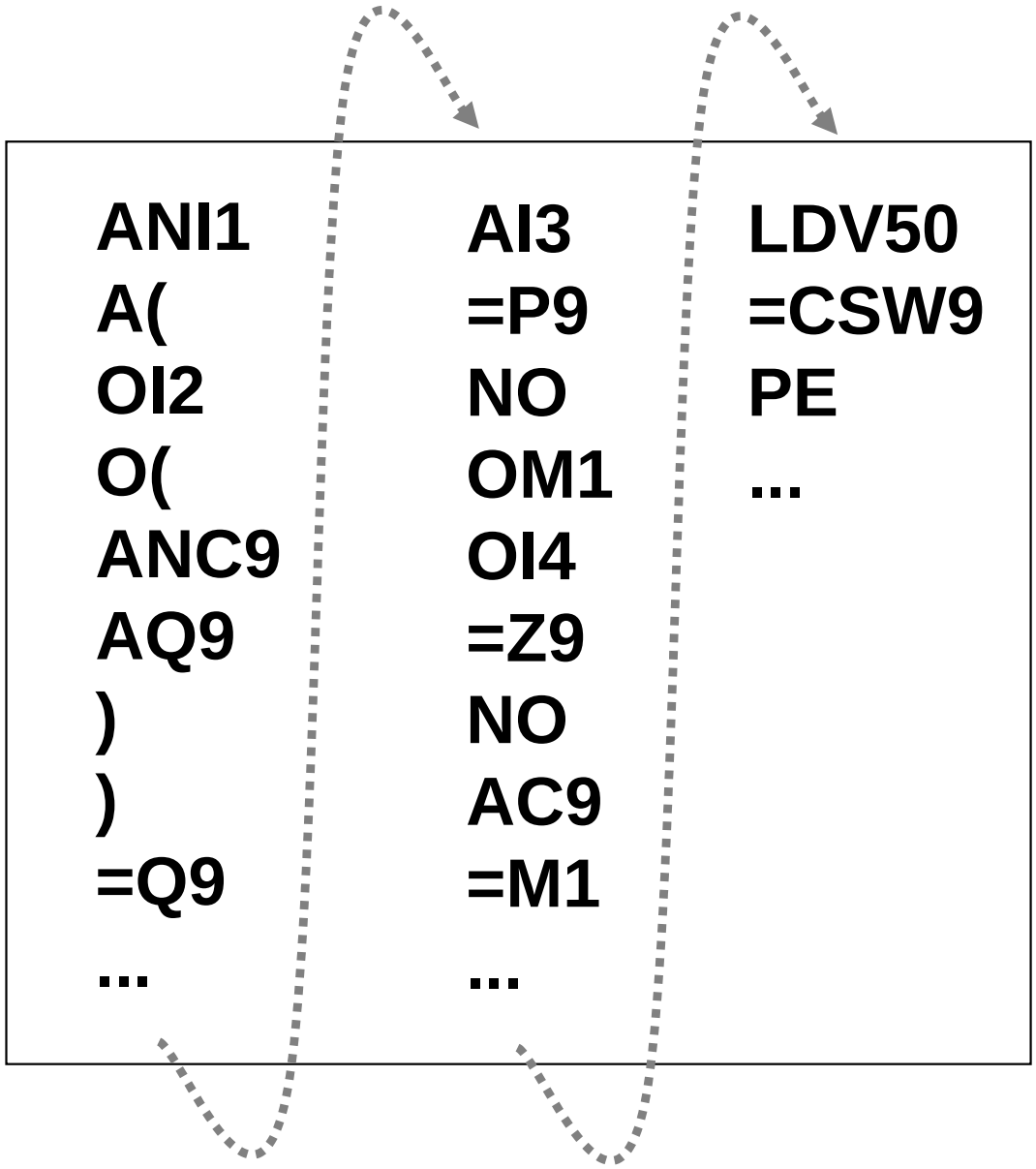
```
LD      %M12
AND     %I1.0
ANDN    %I1.1
OR      %M10
ST      %Q2.0
```

Sequential Function Chart (GRAFCET)

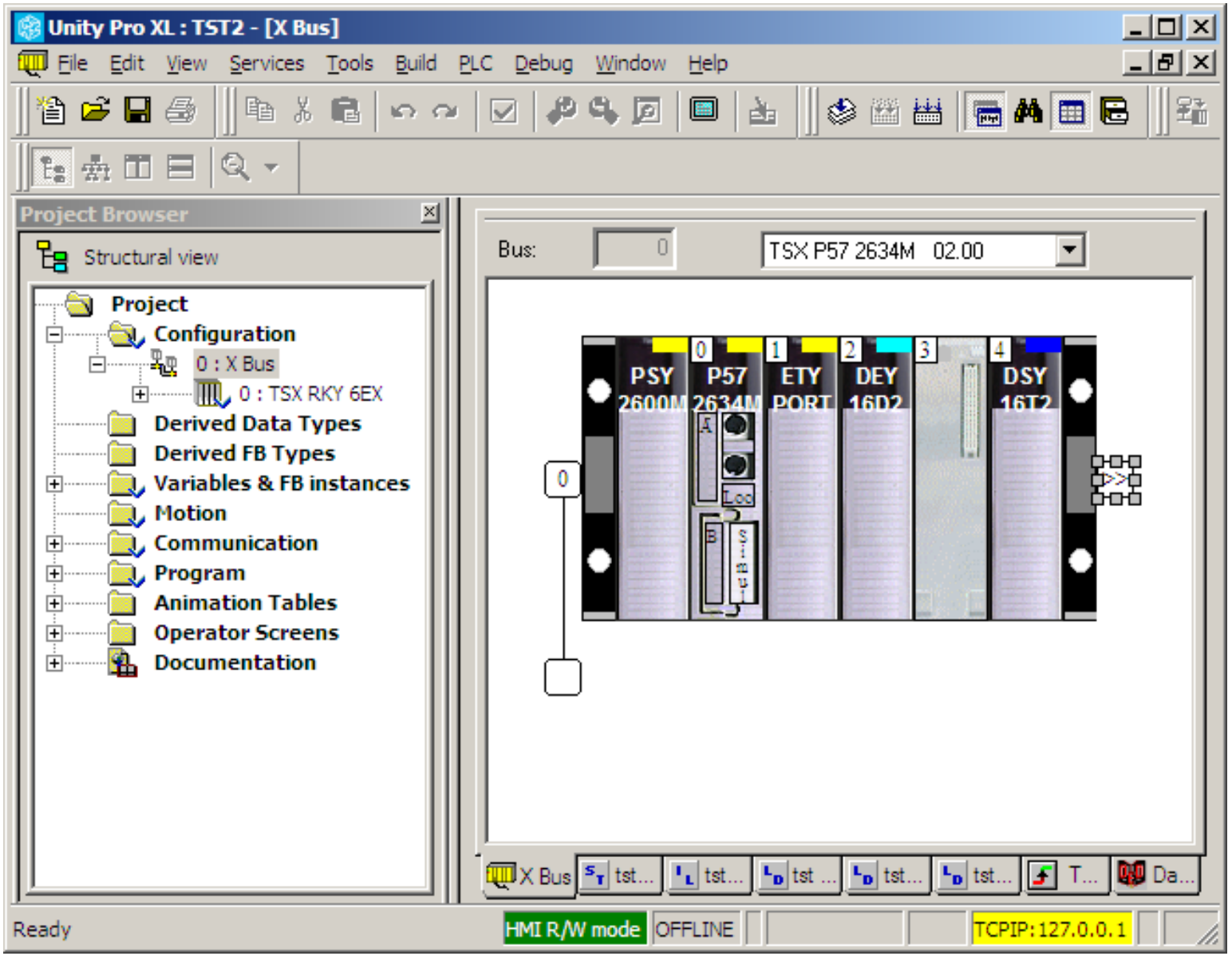


Instruction list

Antique PLC

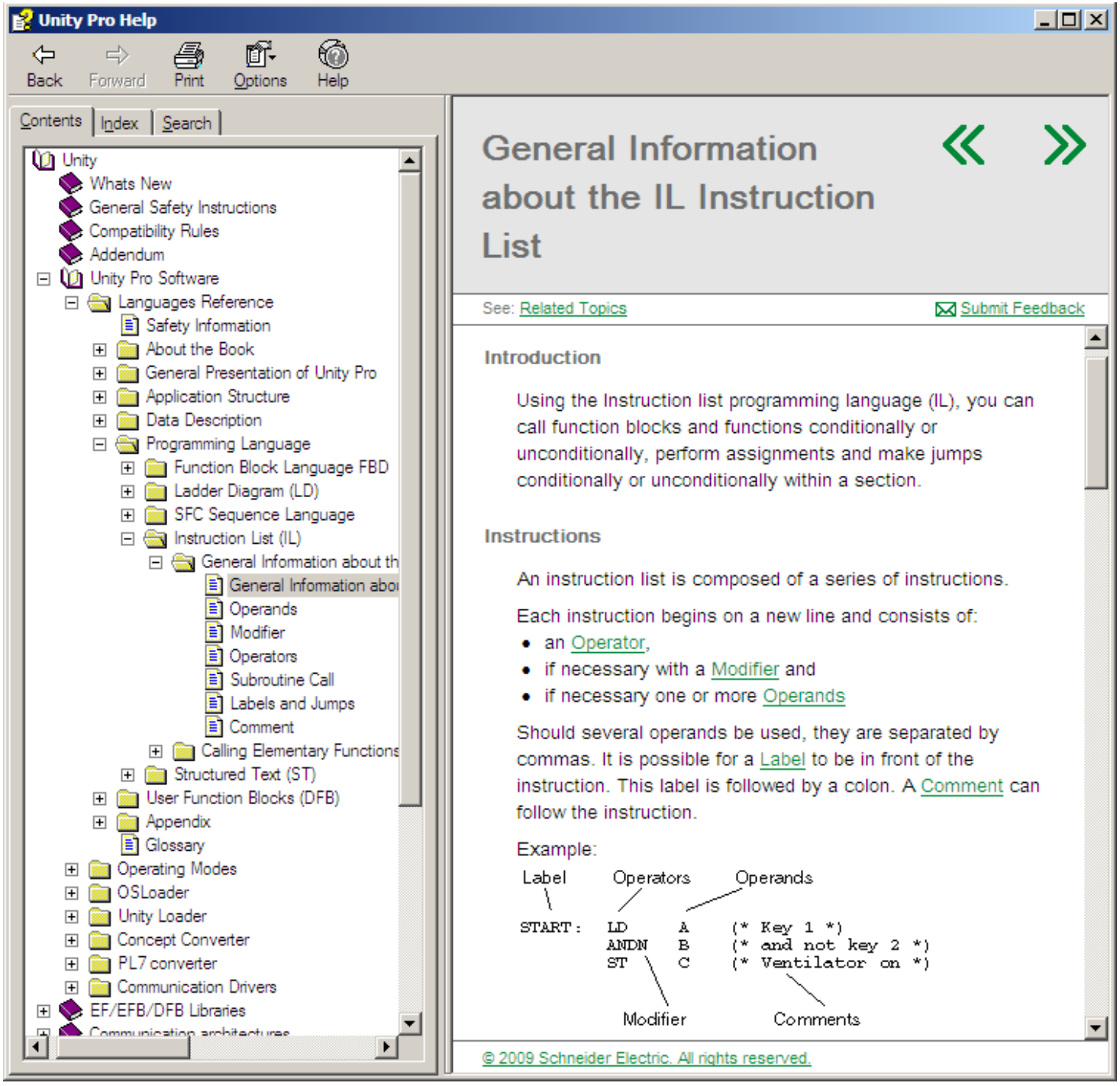


Instruction list *Reference – see Unity Pro dev. environment*



Instruction list

Reference – Unity Pro Help

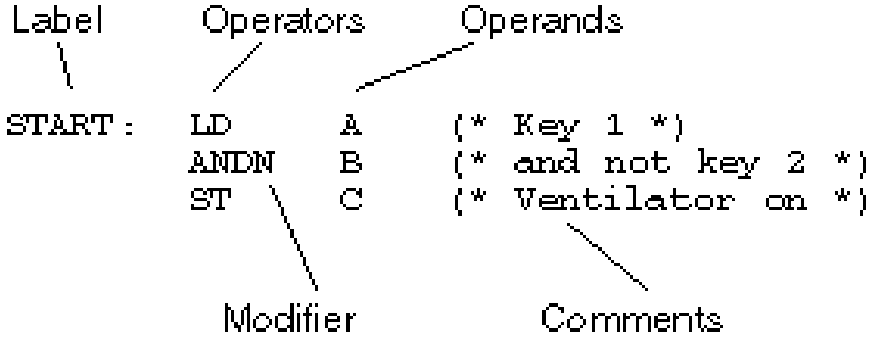


Instruction list *Reference – Unity Pro Help*

PLC Program = {Sections}, Section = {Sequences}
One sequence is equivalent to one or more rungs in *ladder diagram*.
Each section can be programmed in Ladder, **Instruction List**, or Structured Text.

IL is a so-called accumulator orientated language, i.e. each instruction uses or alters the current content of the accumulator (a form of internal cache). IEC 61131 refers to this accumulator as the "result". For this reason, an instruction list should always begin with the LD operand ("Load in accumulator command").

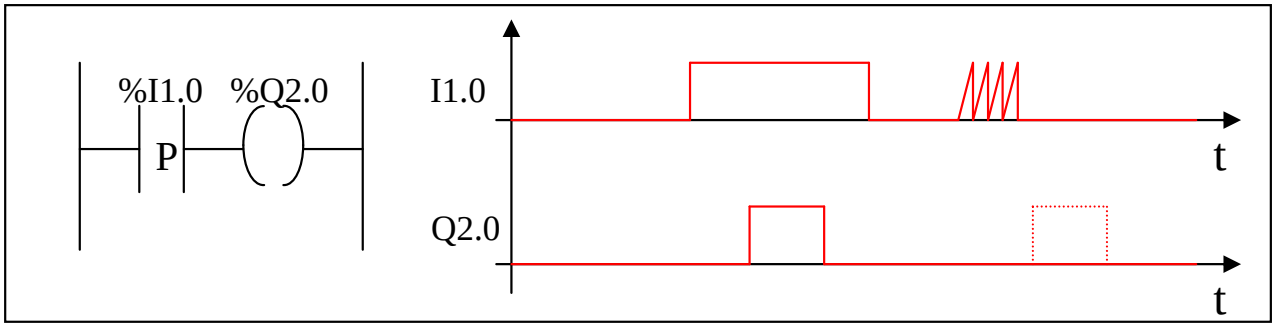
An **Instruction list (IL)** is composed of a series of instructions. Each instruction begins on a new line and consists of:
- an **Operator**,
- if necessary with a **Modifier** and
- if necessary one or more **Operands**

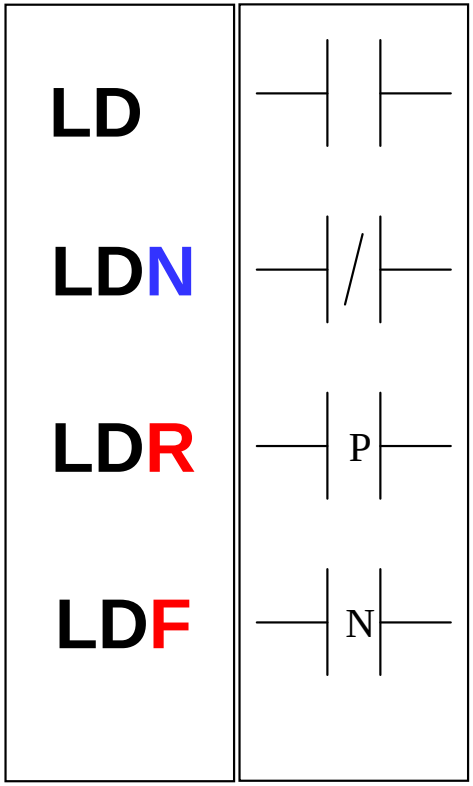


Instruction list

Basic Instructions

Load





Open contact: contact is active (result is 1) while the control bit is 1.

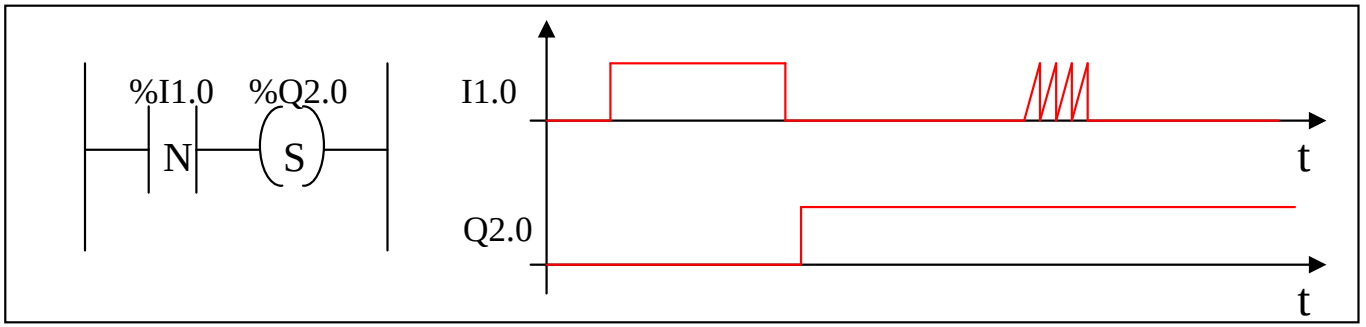
Close contact: contact is active (result is 1) while the control bit is 0.

Contact in the rising edge: contact is active during a scan cycle where the control bit has a rising edge.

Contact in the falling edge: contact is active during a scan cycle where the control bit has a falling edge.

Instruction list

Basic Instructions

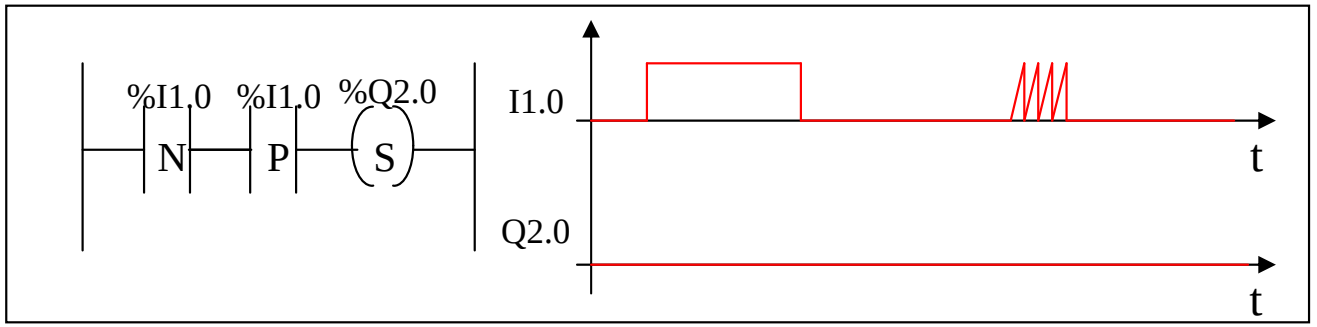


Store

ST	The result of the logic function activates the coil.
STN	The inverse result of the logic function activates the coil.
S	The result of the logic function energizes the relay (sets the latch).
R	The result of the logic function de-energizes the relay (resets the latch)..

Instruction list

Basic Instructions



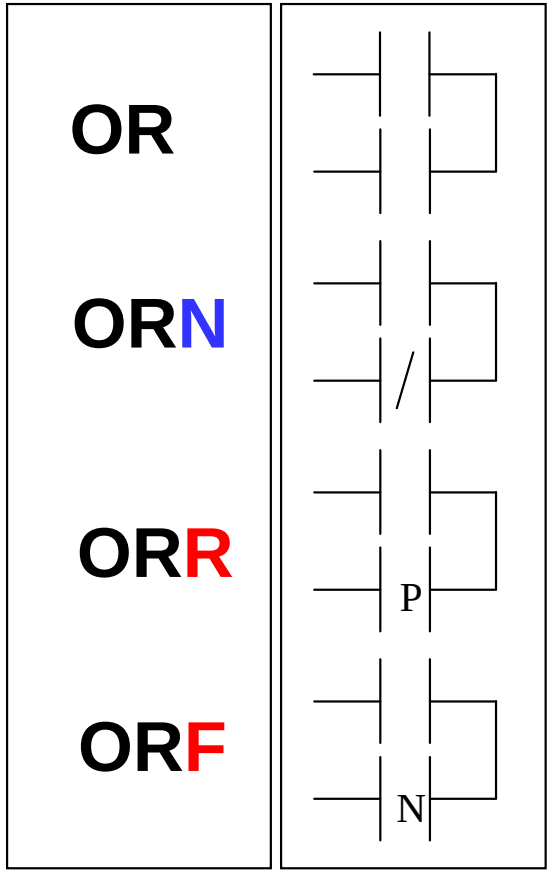
AND

AND	AND of the operand with the result of the previous logical operation.
ANDN	AND of the operand with the inverted result of the previous logical operation.
ANDR	AND of the rising edge with the result of the previous logical operation.
ANDF	AND of the falling edge with the result of the previous logical operation.

Instruction list

Basic Instructions

OR



OR of the operand with the result of the previous logical operation.

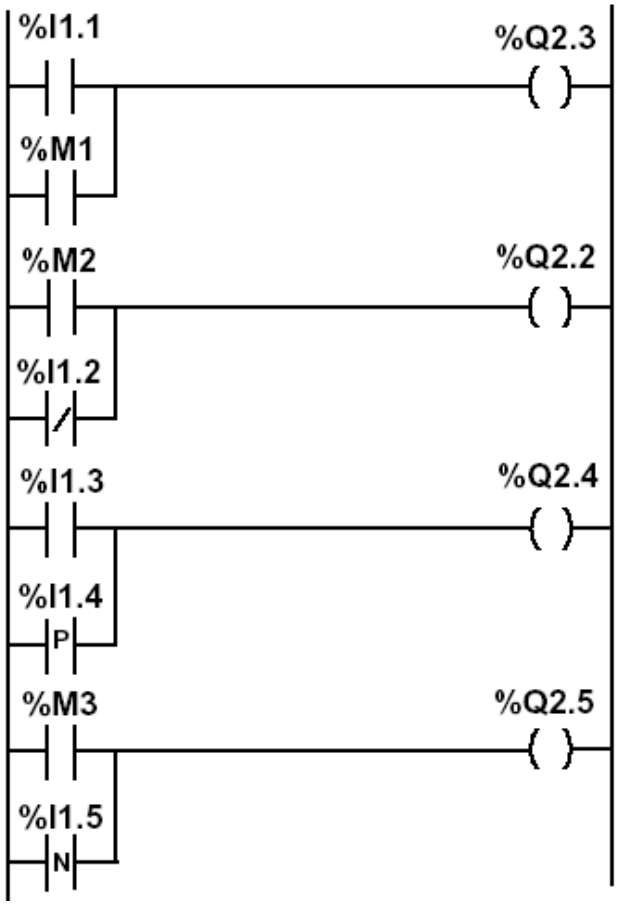
OR of the operand with the inverted result of the previous logical operation.

OR of the rising edge with the result of the previous logical operation.

OR of the falling edge with the result of the previous logical operation.

Instruction list

Example:

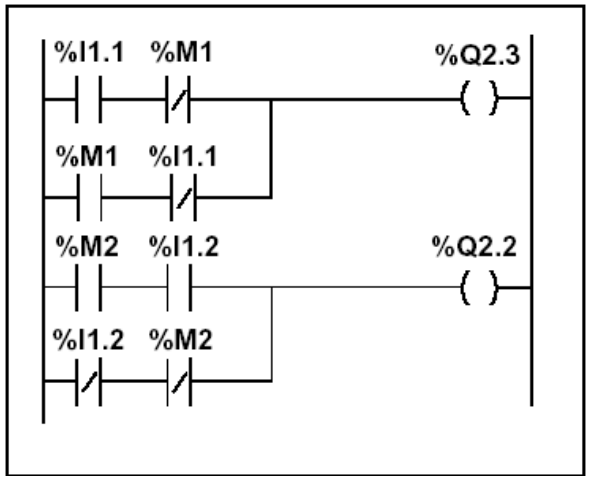



```
LD %I1.1
OR %M1
ST %Q2.3

LD %M2
ORN %I1.2
ST %Q2.2

LD %I1.3
ORR %I1.4
ST %Q2.4

LD %M3
ORF %I1.5
ST %Q2.5
```

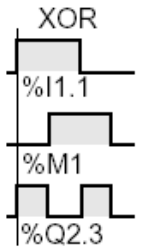
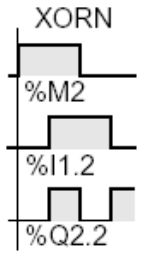
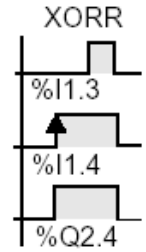
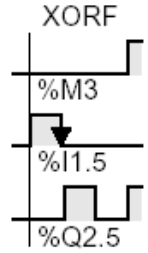
Instruction list

Basic Instructions

XOR



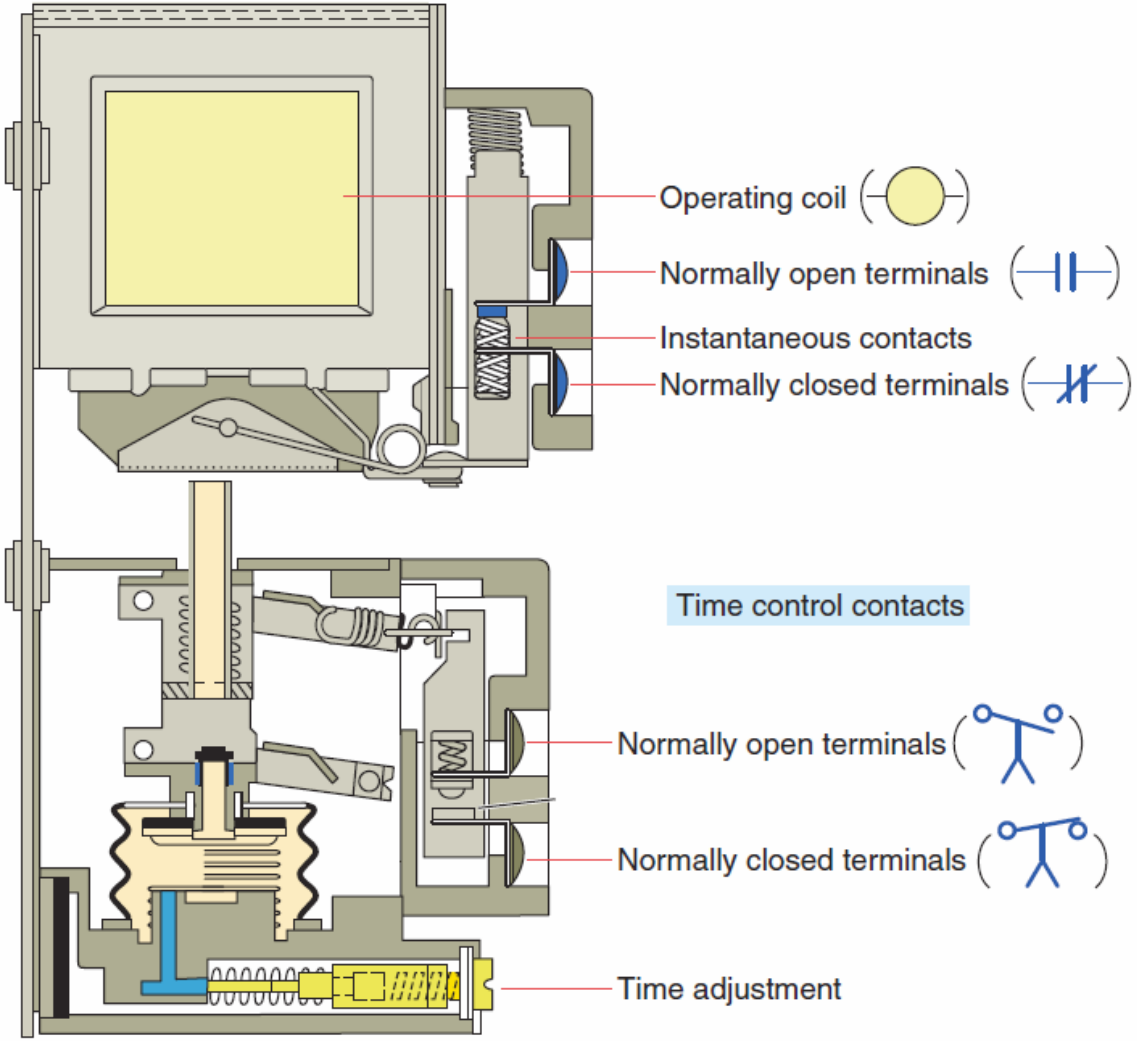

```
...
LD      %I1.1
XOR     %M1
ST      %Q2.3
LD      %M2
XOR     %I1.2
ST      %Q2.2
...
```

Instruction list	Structured text	Description	Timing diagram
XOR	XOR	OR Exclusive between the operand and the previous instruction's Boolean result	
XORN	XOR (NOT...)	OR Exclusive between the operand inverse and the previous instruction's Boolean result	
XORR	XOR (RE...)	OR Exclusive between the operand's rising edge and the previous instruction's Boolean result	
XORF	XOR (FE...)	OR Exclusive between the operand's falling edge and the previous instruction's Boolean result.	

Instruction list

Temporized Relays or Timers (pneumatic)

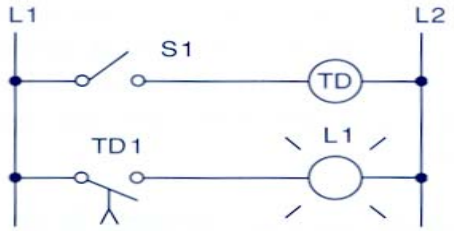
Pneumatic timing relay



The instantaneous contacts change state as soon as the timer coil is powered.
The delayed contacts change state at the end of the time delay.

Instruction list

Example:



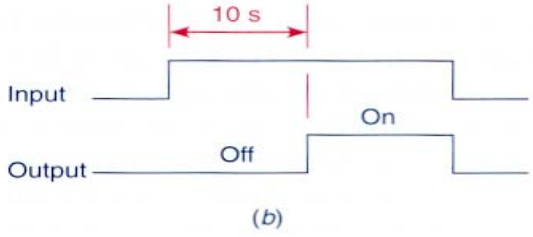
Sequence of operation:
S1 open, TD de-energized, TD1 open, L1 off.

S1 closes, TD energizes, timing period starts, TD1 is still open, L1 is still off.

After 10 s, TD1 closes, L1 is switched on.

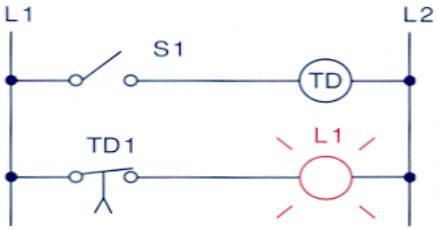
S1 is opened, TD de-energizes, TD1 opens instantly, L1 is switched off.

(*a*)



(*b*)

Fig. 7-3
On-delay timer circuit (NOTC contact). (a) Operation. (b) Timing diagram.



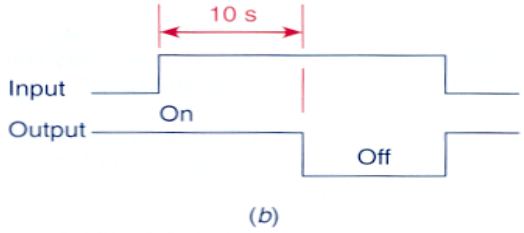
Sequence of operation:
S1 open, TD de-energized, TD1 closed, L1 on.

S1 closes, TD energizes, timing period starts, TD1 is still closed, L1 is still on.

After 10 s, TD1 opens, L1 is switched off.

S1 is opened, TD de-energizes, TD1 closes instantly, L1 is switched on.

(*a*)

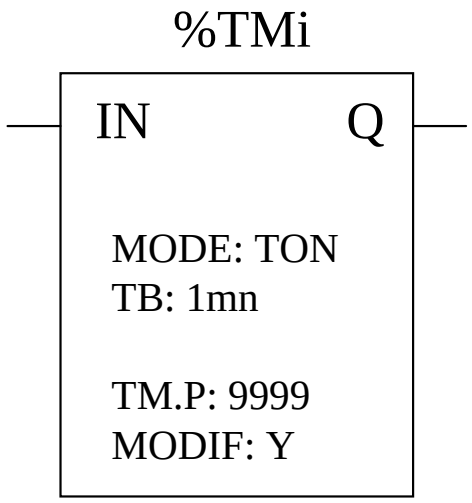


(*b*)

Fig. 7-4
On-delay timer circuit (NCTO contact). (a) Operation. (b) Timing diagram.

Instruction list

Temporized Relays or Timers

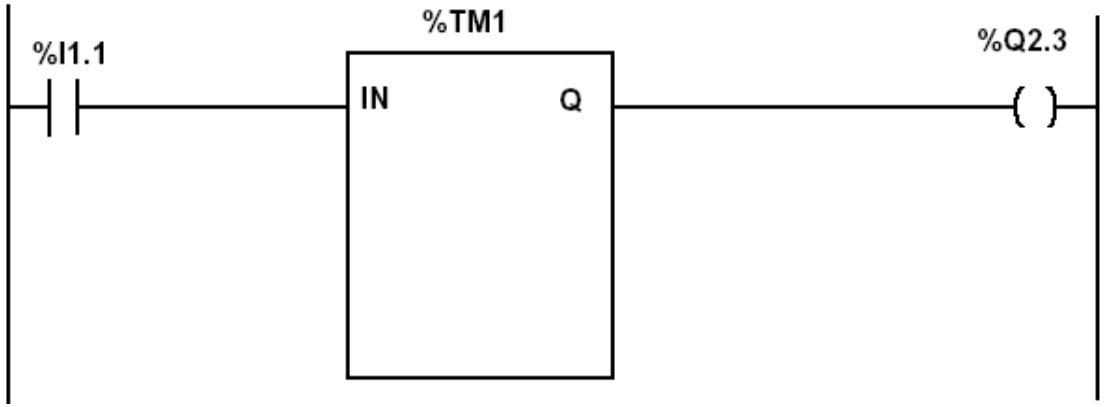


Characteristics:

Identifier:	%TMi	0..63 in the TSX37
Input:	IN	to activate
Mode:	TON	On delay
	TOFF	Off delay
	TP	Monostable
Time basis:	TB	1mn (def.), 1s, 100ms, 10ms
Programmed value:	%TMi.P	0...9999 (def.) period=TB*TMi.P
Actual value:	%TMi.V	0...TMi.P (can be real or tested)
Modifiable:	Y/N	can be modified from the console

Instruction list

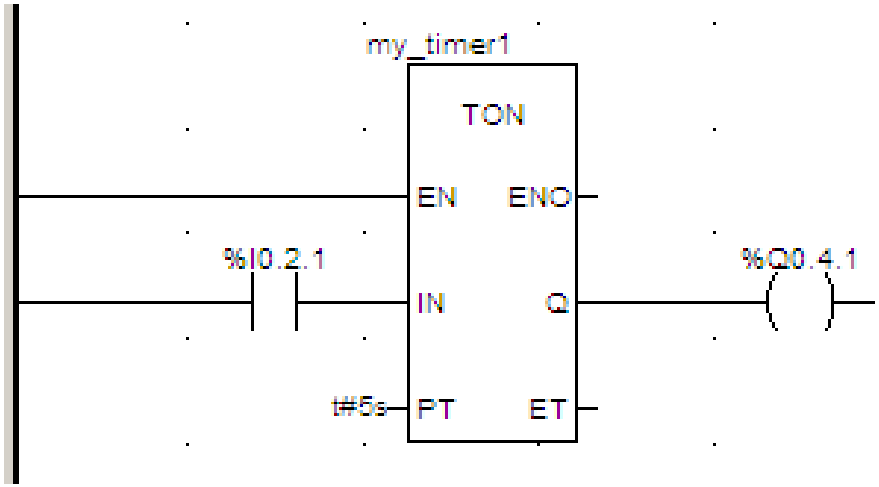
Temporized Relays or Timers (PL7)




```
LD      %I1.1
IN      %TM1
LD      %TM1.Q
ST      %Q2.3
```

Instruction list

Temporized Relays or Timers




```
CAL my_timer1 (IN := %I0.2.1 (*BOOL*),
               PT := t#5s    (*TIME*),
               Q =>  %Q0.4.1(*BOOL*),
               ET => my_var  (*TIME*))
```

Instruction list

Counters

Some applications...

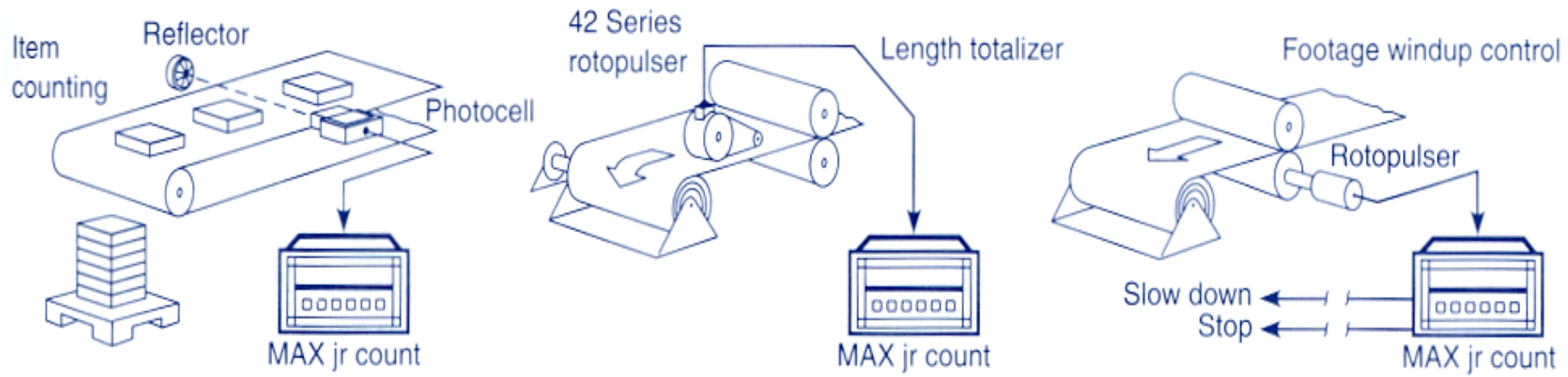


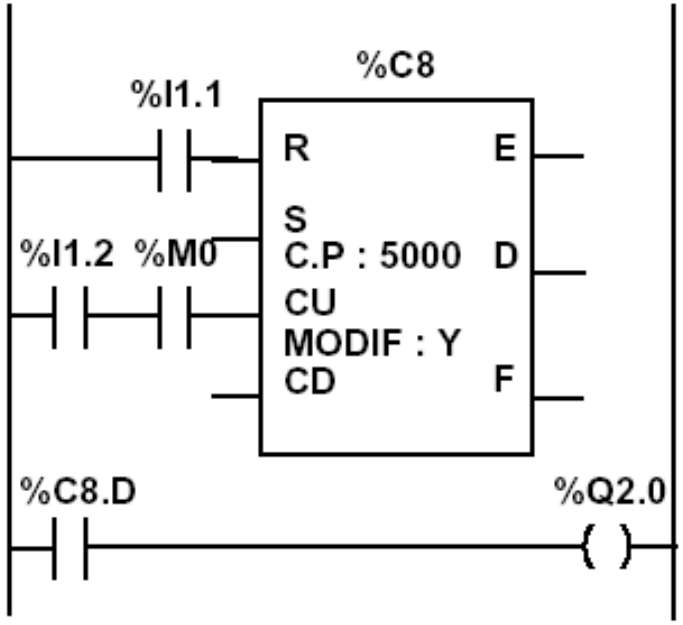
Fig. 8-3

Counter applications. *(Courtesy of Dynapar Corporation, Gurnee, Illinois.)*

Instruction list

Counters (PL7)

Example:

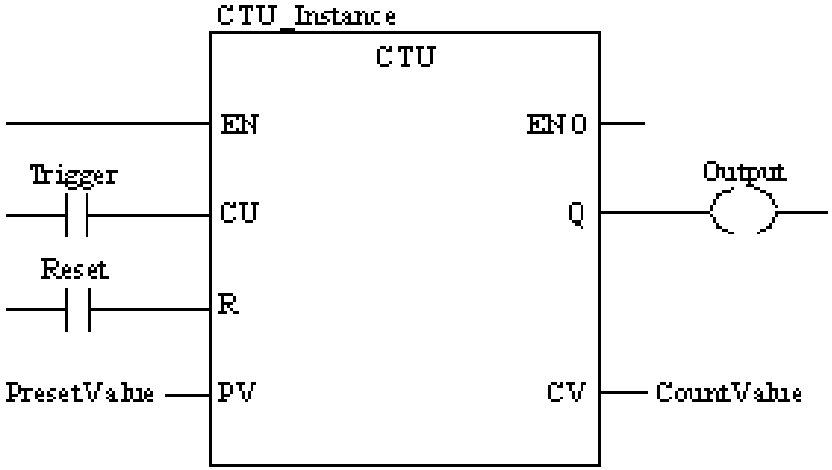


Instruction list language

```
LD %I1.1
R   %C8
LD  %I1.2
AND %M0
CU  %C8
LD  %C8.D
ST  %Q2.0
```

Ladder diagram

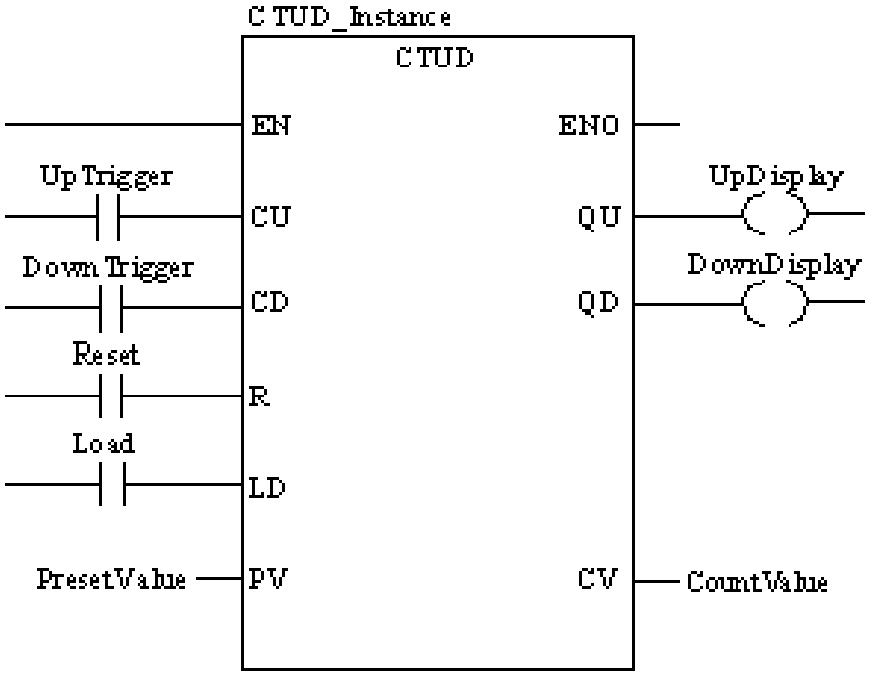
Counters in Unity Pro



CU "0" to "1" => CV is incremented by 1

CV ≥ PV => Q:=1

R=1 => CV:=0



CU "0" to "1" => CV is incremented by 1
CD "0" to "1" => CV is decremented by 1

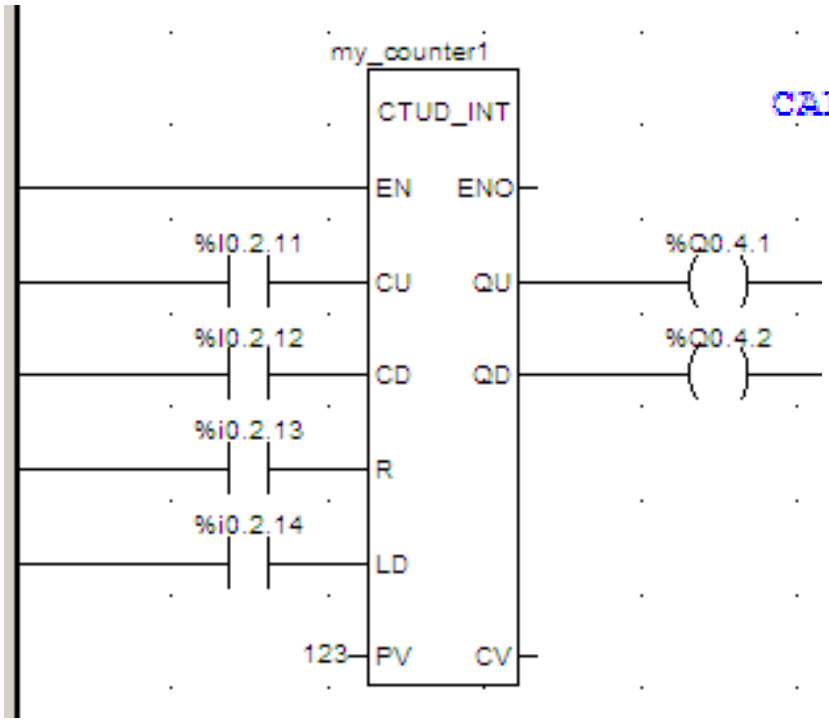
CV ≥ PV => QU:=1
CV ≤ 0 => QD:=1

R=1 => CV:=0 **LD=1** => CV:=PV
R has precedence over LD

NOTE: counters are saturated such that no overflow occurs

Ladder diagram

Counters in Unity Pro




```
CAL my_counter1 (CU := %I0.2.11 (*BOOL*),
                 CD := %I0.2.12 (*BOOL*),
                 R  := %I0.2.13 (*BOOL*),
                 LD := %I0.2.14 (*BOOL*),
                 PV := 123 (*INT*),
                 QU => %Q0.4.1 (*BOOL*),
                 QD => %Q0.4.2 (*BOOL*),
                 CV => %MW100 (*INT*))
```

Instruction list

Numerical Processing

Algebraic and Logic Functions (PL7)

```
LD      [%MW50>10]
ST      %Q2.2
LD      %I1.0
[%MW10:=%KW0+10]
LDF     %I1.2
[INC%MW100]
```

Instruction list

Numerical Processing

Arithmetic Functions

+	addition of two operands	**SQRT**	square root of an operand
-	subtraction of two operands	**INC**	incrementation of an operand
*	multiplication of two operands	**DEC**	decrementation of an operand
/	division of two operands	**ABS**	absolute value of an operand
REM	remainder from the division of 2 operands		

Operands

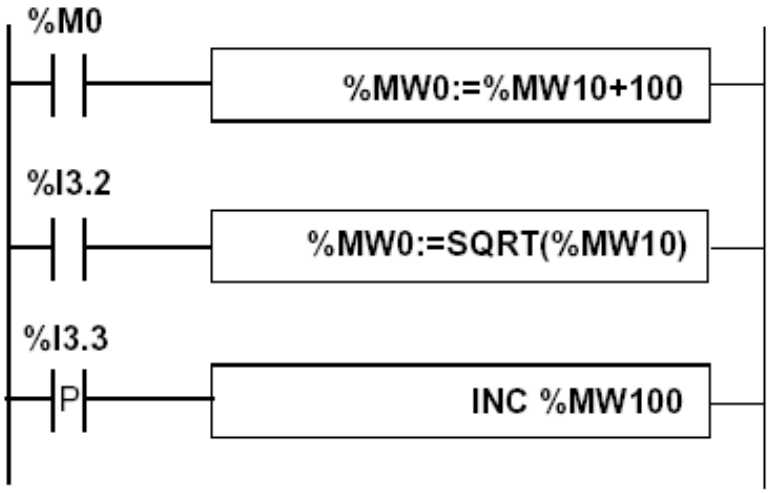
Type	Operand 1 (Op1)	Operand 2 (Op2)
Indexable words	%MW	%MW,%KW,%Xi.T
Non-indexable words	%QW,%SW,%NW,%BLK	Imm.Val.,%IW,%QW,%SW,%NW, %BLK, Num.expr.
Indexable double words	%MD	%MD,%KD
Non-indexable double words	%QD,%SD	Imm.Val.,%ID,%QD,%SD, Numeric expr.

Instruction list

Numerical Processing

Example:

Arithmetic functions



PL7:

Instruction list language

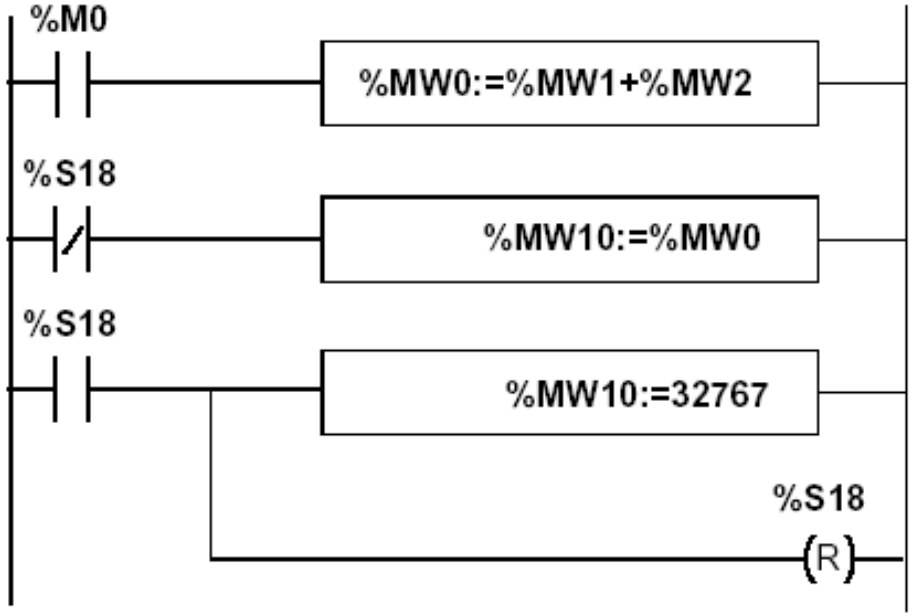
```
LD   %M0
[%MW0:=%MW10+100]

LD   %I3.2
[%MW0:=SQRT(%MW10)]

LD   %I3.3
[INC %MW100]
```

Instruction list

Numerical Processing

Example:

Arithmetic functions



PL7:

Example in instruction list language:

```
LD     %M0
[%MW0:=%MW1+%MW2]
LDN    %S18
[%MW10:=%MW0]
LD     %S18
[%MW10:=32767]
R     %S18]
```

Use of a system variable:

%S18 – flag de overflow

Instruction list

Numerical Processing

Logic Functions

AND	AND (bit by bit) between two operands
OR	logical OR (bit by bit) between two operands
XOR	exclusive OR (bit by bit) between two operands
NOT	logical complement (bit by bit) of an operand

Comparison instructions are used to compare two operands.

- **>**: tests whether operand 1 is greater than operand 2,
- **>=**: tests whether operand 1 is greater than or equal to operand 2,
- **<**: tests whether operand 1 is less than operand 2,
- **<=**: tests whether operand 1 is less than or equal to operand 2,
- **=**: tests whether operand 1 is different from operand 2.

Operands

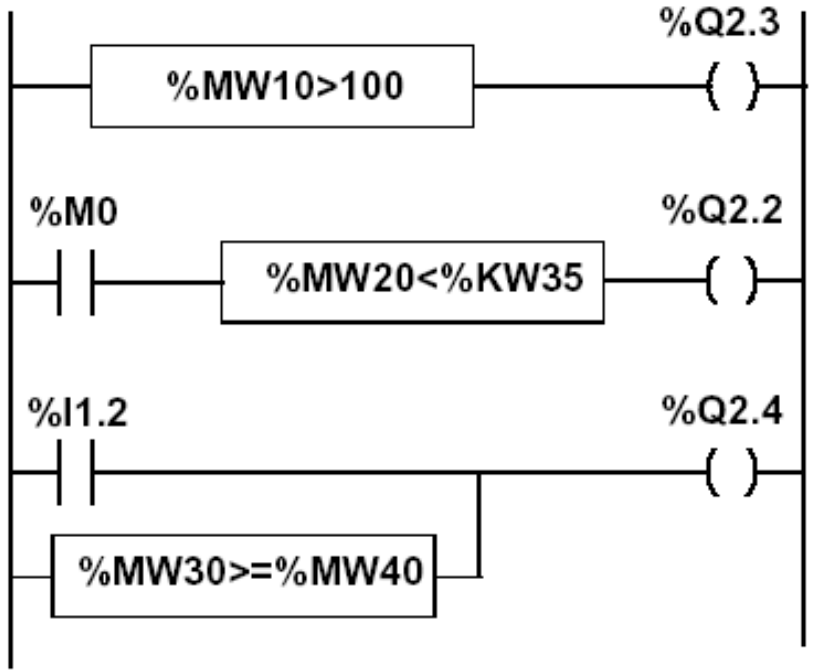
Type	**Operands 1 and 2 (Op1 and Op2)**
Indexable words	%MW,%KW,%Xi.T
Non-indexable words	Imm.val.,%IW,%QW,%SW,%NW,%BLK, Numeric Expr.
Indexable double words	%MD,%KD
Non-indexable double words	Imm.val.,%ID,%QD,%SD,Numeric expr.

Instruction list

Numerical Processing

Example:

Logic functions



PL7:

Instruction list language

```
LD    [%MW10>100]
ST    %Q2.3
LD    %M0
AND   [%MW20<%KW35]
ST    %Q2.2
LD    %I1.2
OR    [%MW30>=%MW40]
ST    %Q2.4
```

Instruction list

Numerical Processing

Priorities on the execution of the operations

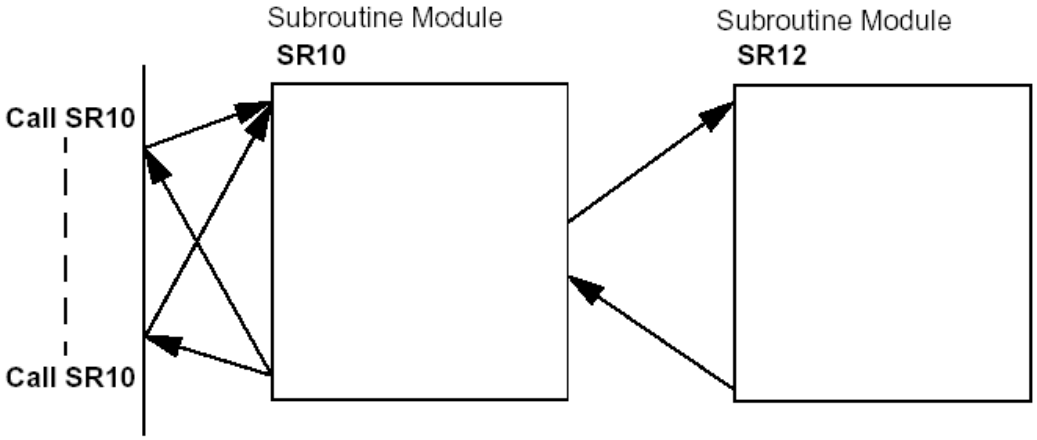
Rank	Instruction
1	Instruction to an operand
2	*,/,REM
3	+,-
4	<,>,<=,>=
5	=,<>
6	AND
7	XOR
8	OR

Instruction list

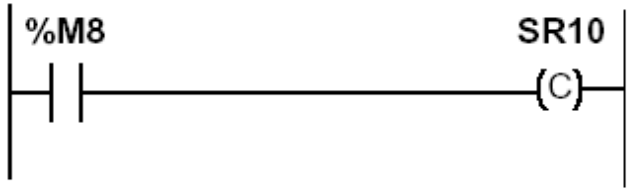
Structures for Control of Flux

Subroutines

Call and Return



Ladder language:



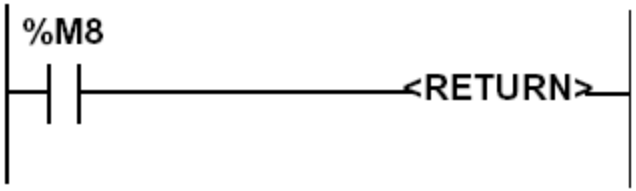
Instruction list language:

```
LD   %M8
CAL  SR10
```

PL7

Unity Pro

Ladder language



Instruction list language

```
LD   %M8
RETC
```

Instruction list

Structures for Control of Flux

JUMP instructions:

Conditional and unconditional

Jump instructions are used to go to a programming line with an %Li label address:

- **JMP**: unconditional program jump
- **JMPC**: program jump if the instruction's Boolean result from the previous test is set at 1
- **JMPCN**: program jump if the instruction's Boolean result from the previous test is set at 0. %Li is the label of the line to which the jump has been made (address i from 1 to 999 with maximum 256 labels)

Instruction list

Structures for Control of Flux

Example:

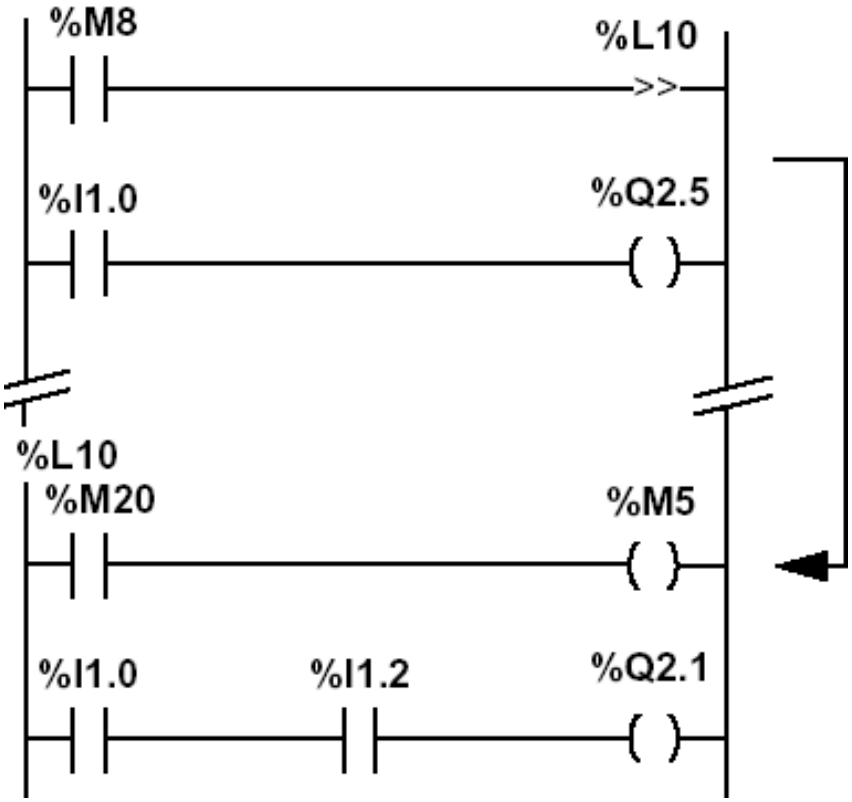
Use of jump instructions

Instruction list language

```
 _
LD      %M8
JMPC    %L10
LD      %I1.0
ST      %Q2.5

----------
%L10:
LD     %M20
ST     %M5
LD     %I1.0
AND    %I1.2
ST     %Q2.1
```

Jump to label %L10, if %M8 =1

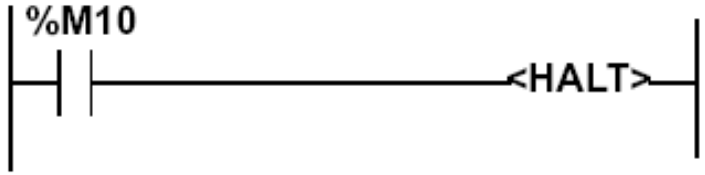
Ladder



Instruction list

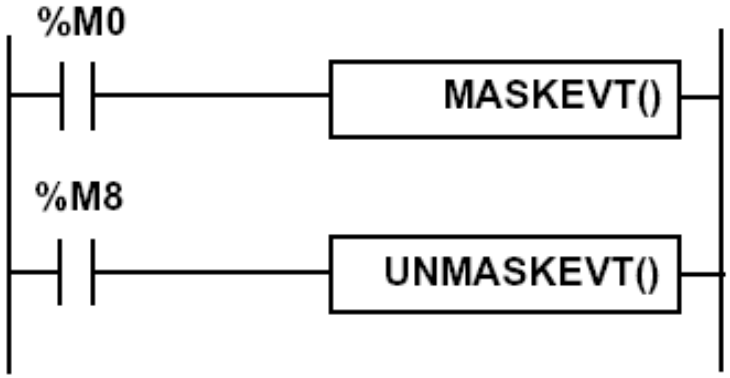
Structures for Control of Flux

Halt



Stops all processes!

Events masking



Instruction list

There are other advanced instructions (see manual)

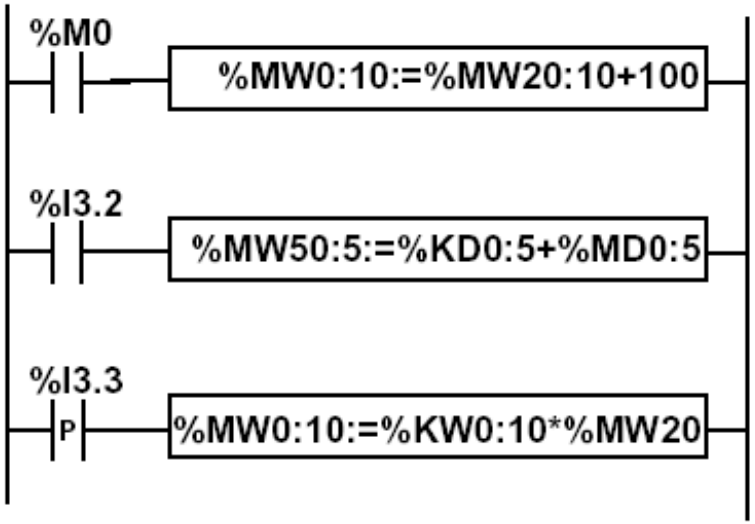
- **Monostable**
- **Registers of 256 words (LIFO ou FIFO)**
- ***DRUMs***
- **Comparators**
- ***Shift-registers***

  ...
- **Functions to manipulate *floats***
- **Functions to convert bases and types**

Instruction list

Numerical Tables

Type	Format	Maximum address	Size	Write access
Internal words	Simple length	%MWi:L	i+L<=Nmax (1)	Yes
	Double length	%MWDi:L	i+L<=Nmax-1 (1)	Yes
	Floating point	%MFi:L	i+L<=Nmax-1 (1)	Yes
Constant words	Single length	%KWi:L	i+L<=Nmax (1)	No
	Double length	%KWDi:L	i+L<=Nmax-1 (1)	No
	Floating point	%KFi:L	i+L<=Nmax-1 (1)	No
System word	Single length	%SW50:4 (2)	-	Yes



PL7:

Instruction list language

```
LD %M0
[%MW0:10:=%MW20:10+100]

LD %I3.2
[%MD50:5:=%KD0:5+%MD0:5]
```

DOLOG80

PLC AEG A020 Plus:

Inputs:
- 20 binary with opto-couplers
- 4 analogs (8 bits, 0-10V)

Outputs:
- 16 binary with relays of 2A
- 1 analogs (8 bits, 0-10V)

Interface for progr.: RS232

Processador:
- 8031
- 2 Kbytes de RAM
- 2 Kbytes EEPROM => 896 instructions
- **Average cycle time: 6.5 ms**

PLC AEG A020 Plus

DOLOG80

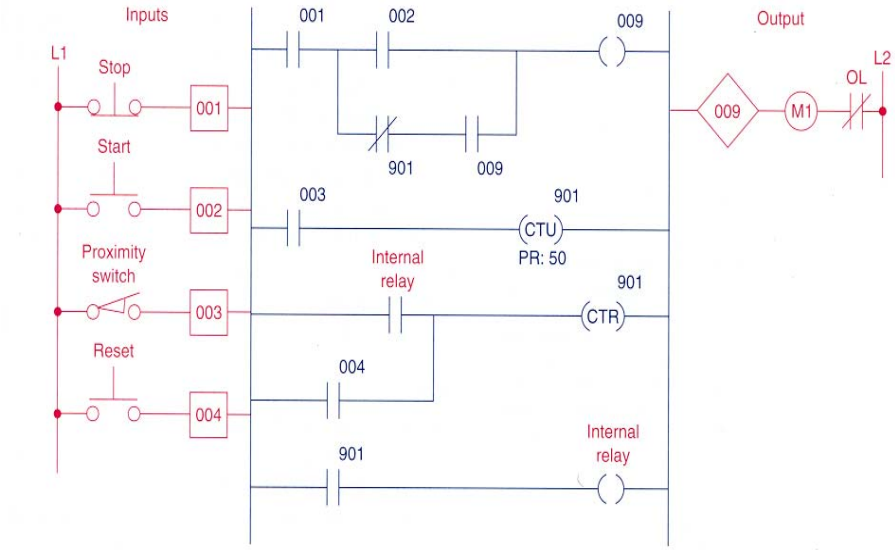
OPERANDS

- I1 to I20 Binary inputs
- Q1 to Q16 Binary outputs
- M1 to M128 Auxiliary memory
- T1 to T8 *Timers* (base 100ms)
- T9 to T16 *Timers* (base 25ms)
- C1 to C16 16 *bits* counters

DOLOG80 (cont.)

Example:

```
AI1          AI3          LDV50
A(           =P9          =CSW9
OI2          NO           PE
O(           OM1
ANC9         OI4
AQ9          =Z9
)            NO
)            AC9
=Q9          =M1
...          ...
```



(*b*) Program

Fig. 8-13 Conveyor motor program.

Legend:

Stop = I1
Start = I2
Proximity Sensor = I3
Reset = I4
Counter= C9
Internal relay = M1
Motor = Q9