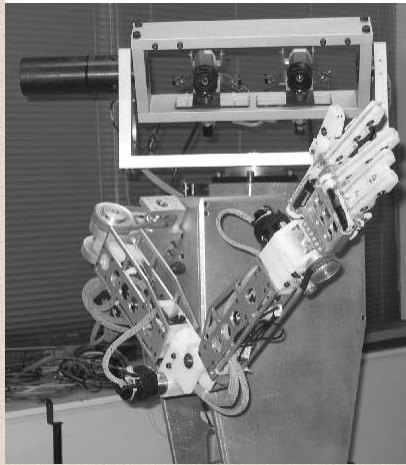




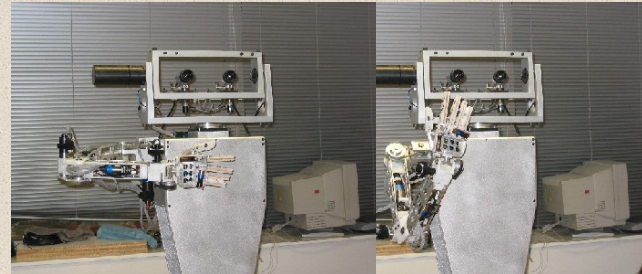
## Topics:

*Learning by imitation and artificial development*



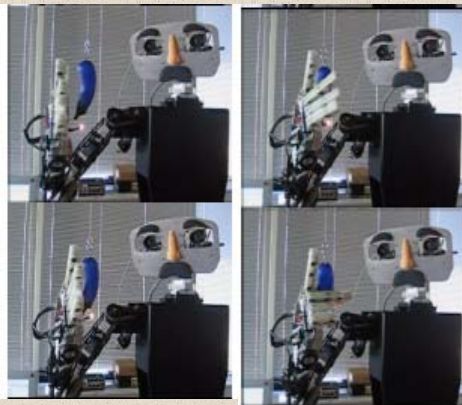
## Sensory-motor Coordination

Sensory-motor Maps  
Redundant manipulators



## World Interaction

near-space mapping  
visual control of grasp  
object affordances learning

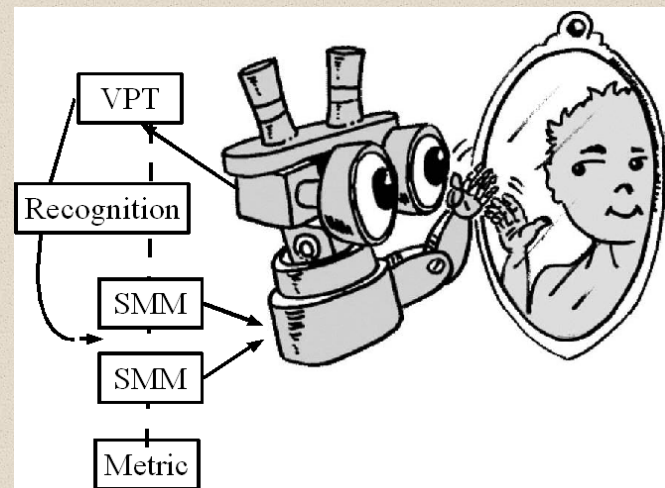


## Imitation

task interpretation  
view-point transformation  
imitation of tasks/gestures



## Architecture



Funding: EU IST-2005-004370